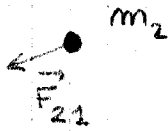


Esercizio sul moto in campo gravitazionale

Leggi di Keplero



$$\vec{F}_{12} = -\vec{F}_{21}$$

$$|\vec{F}_{12}| = |\vec{F}_{21}| = F(r) =$$

$$\frac{G m_1 m_2}{r^2}$$

$$K = G m_1 m_2$$

≡

$$\frac{K}{r^2}$$

Eq. del moto:

$$\begin{cases} m_1 \ddot{\vec{r}}_1 = -\vec{F}_{21} \\ m_2 \ddot{\vec{r}}_2 = \vec{F}_{21} \end{cases}$$

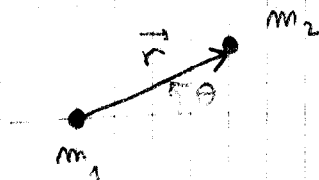
Si possono riscrivere anche come:

$$\begin{cases} m_1 \ddot{\vec{r}}_1 + m_2 \ddot{\vec{r}}_2 = 0 \\ \ddot{\vec{r}}_2 - \ddot{\vec{r}}_1 = \frac{\vec{F}_{21}}{m_2} \left(\frac{1}{m_1} + \frac{1}{m_2} \right) \end{cases}$$

$$\begin{cases} (m_1 + m_2) \ddot{\vec{r}}_{CM} = 0 \\ \frac{m_1 m_2}{m_1 + m_2} \ddot{\vec{r}} = \vec{F}_{21} ; \vec{r} = \vec{r}_2 - \vec{r}_1 \end{cases}$$

⇒ C.M. va di moto rettilineo uniforme ⇒ mu' netto sul SR CM. ⇒

$$\mu \ddot{\vec{r}} = -\frac{K}{r^2} \hat{r}$$



equazione non banale da risolvere!

Procediamo per altro modo: costanti del moto sono

1) energia E

2) mom. angolare \vec{L}_{CM} (sono in SR CM)

1) $E = \frac{1}{2} \mu v^2 + U(r)$

$U(r) = U(\infty) = - \int_{\infty}^r (-\frac{k}{x^2}) dx = -\frac{k}{r}$

$\Rightarrow E = \frac{1}{2} \mu (\dot{r}^2 + r^2 \dot{\theta}^2) - \frac{k}{r}$

2) $\vec{L}_{CM} = \mu \vec{r} \times \vec{v}$

$\vec{L} = m_1 \vec{r}_1 \times \vec{v}_1 + m_2 \vec{r}_2 \times \vec{v}_2$

$$\begin{cases} m_1 \vec{r}_1 + m_2 \vec{r}_2 = m_t \vec{r}_{CM} \\ m_1 \vec{v}_1 + m_2 \vec{v}_2 = m_t \vec{v}_{CM} \end{cases} \Leftrightarrow \begin{cases} \vec{L}_1 = \vec{L}_{CM} - \frac{m_2}{m_t} \vec{r} \times \vec{v} \\ \vec{L}_2 = \vec{L}_{CM} + \frac{m_1}{m_t} \vec{r} \times \vec{v} \end{cases}$$

$$\begin{cases} \vec{r}_1 = \vec{r}_{CM} - \frac{m_2}{m_t} \vec{r} \\ \vec{r}_2 = \vec{r}_{CM} + \frac{m_1}{m_t} \vec{r} \end{cases}$$

$\Rightarrow \vec{L} = m_1 \left[\vec{r}_{CM} \times \vec{v}_{CM} - \frac{m_2}{m_t} \vec{r}_{CM} \times \vec{v} - \frac{m_2}{m_t} \vec{r} \times \vec{v}_{CM} + \frac{m_2^2}{m_t^2} \vec{r} \times \vec{v} \right]$

$+ m_2 \left[\vec{r}_{CM} \times \vec{v}_{CM} + \frac{m_1}{m_t} \vec{r}_{CM} \times \vec{v} + \frac{m_1}{m_t} \vec{r} \times \vec{v}_{CM} + \frac{m_1^2}{m_t^2} \vec{r} \times \vec{v} \right]$

$= (m_1 + m_2) \vec{r}_{CM} \times \vec{v}_{CM} + \frac{m_1 m_2}{m_t} \frac{(m_2 + m_1)}{m_t} \vec{r} \times \vec{v}$

$= M_{tot} \vec{r}_{CM} \times \vec{v}_{CM} + \mu \vec{r} \times \vec{v}$

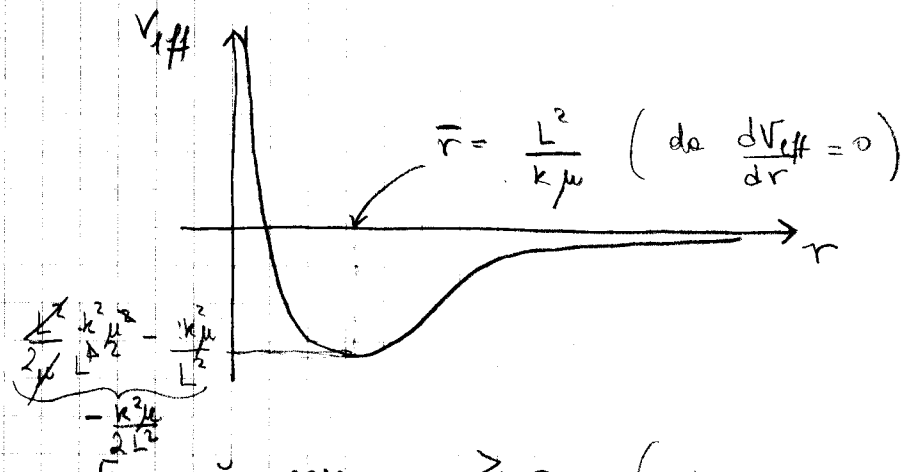
$\Rightarrow \vec{L}_{CM} = \mu r^2 \dot{\theta} \hat{z}$ (\perp al foglio)

\vec{L}_{CM} si conserva \Rightarrow il moto è piano !!

$$E = \frac{1}{2} \mu \dot{r}^2 + \frac{1}{2} \mu r^2 \dot{\theta}^2 - \frac{k}{r} = \frac{1}{2} \mu \dot{r}^2 + \frac{L^2}{2\mu r^2} - \frac{k}{r}$$

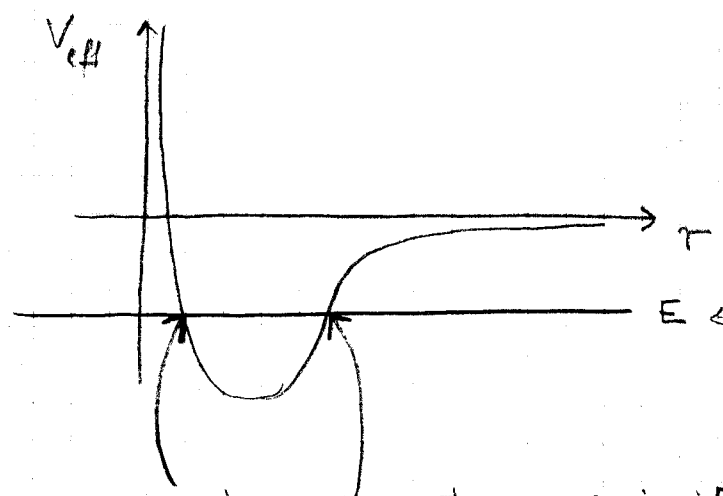
Che traiettoria fa?

Consideriamo $V_{eff}(r) \stackrel{\text{definito}}{=} \frac{L^2}{2\mu r^2} - \frac{k}{r}$



E può essere ≥ 0 (per esempio a $t=0$ sono $v_0 \neq 0$ e $r = r_0 \Rightarrow E = -\frac{k}{r_0}$)

$E < 0$



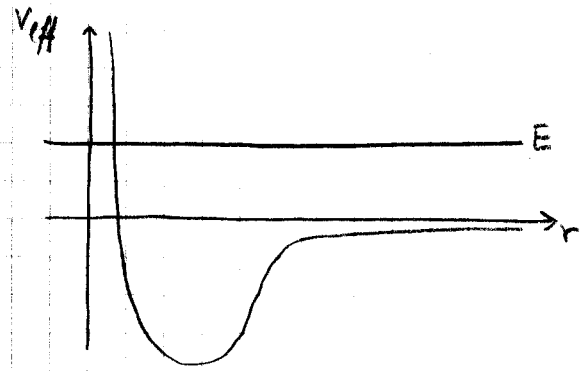
$E \leftarrow$ vediamo che è un'ellisse

esistono 2 punti in cui $V_{eff}(r) = E \Rightarrow r = r_{min}$
 \Rightarrow sono r_{max} e r_{min}
 \Rightarrow traiettoria chiusa

$E = -\frac{1}{2} \mu \frac{k^2}{L^2}$

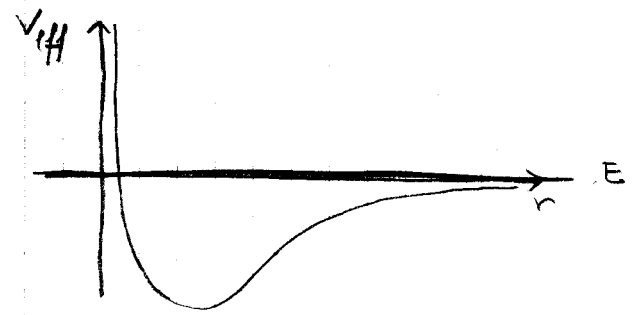
In particolare $\mu E = V_{eff}(\bar{r}) \quad \dot{r} = 0$ sempre
 \Rightarrow traiettoria circolare

$E > 0$



È una distanza minima, ma la traiettoria è aperta. Vedremo che si tratta di un'iperbole

$E = 0$



La traiettoria è aperta e $\dot{r} = 0$ all'infinito ($E = 0$ e $V(r) = 0$ per $r = \infty$). Vedremo che si tratta di una parabola.

Risolviamo adesso per bene:

$$E = \frac{1}{2} \mu \dot{r}^2 + \frac{L^2}{2\mu r^2} - \frac{k}{r}$$

$$= \frac{1}{2} \mu \left(\frac{dr}{d\theta} \right)^2 \dot{\theta}^2 + \frac{L^2}{2\mu r^2} - \frac{k}{r} = \frac{1}{2} \mu \left(\frac{dr}{d\theta} \right)^2 \frac{L^2}{\mu^2 r^4} + \frac{L^2}{2\mu r^2} - \frac{k}{r}$$

$$\Rightarrow \frac{1}{r^4} \left(\frac{dr}{d\theta} \right)^2 = \frac{2E\mu}{L^2} - \frac{1}{r^2} + \frac{2\mu k}{L^2} \frac{1}{r}$$

Introduces $u(\theta) = \frac{1}{r(\theta)} \Rightarrow \frac{du}{d\theta} = -\frac{1}{r^2} \frac{dr}{d\theta} \Rightarrow$

$$\left(\frac{du}{d\theta} \right)^2 = \frac{2E\mu}{L^2} - u(\theta)^2 + \frac{2\mu k}{L^2} u(\theta)$$

$$A = \frac{2E\mu}{L^2} ; B = \frac{2\mu k}{L^2}$$

$$\left(\frac{du}{d\theta}\right)^2 = A + B u - u^2$$

Solution: $u(\theta) = \frac{B}{2} - \sqrt{A + \frac{B^2}{4}} \cos\theta$

Verify: $\frac{du}{d\theta} = \left(A + \frac{B^2}{4}\right)^{1/2} \sin\theta \Rightarrow$

$$\left(A + \frac{B^2}{4}\right) \sin^2\theta = A + \frac{B^2}{2} - B \sqrt{A + \frac{B^2}{4}} \cos\theta$$

$$- \frac{B^2}{4} - \left(A + \frac{B^2}{4}\right) \cos^2\theta + B \sqrt{A + \frac{B^2}{4}} \cos\theta$$

$$= \left(A + \frac{B^2}{4}\right) (1 - \cos^2\theta)$$

$$\Rightarrow \left\{ \begin{aligned} r(\theta) &= \frac{1}{\frac{B}{2} - \sqrt{A + \frac{B^2}{4}} \cos\theta} = \frac{l}{1 - e \cos\theta} \end{aligned} \right.$$

$$l = \frac{2}{B} = \frac{L^2}{\mu k}$$

$$e = \frac{2}{B} \sqrt{A + \frac{B^2}{4}} = \sqrt{1 + \frac{4A}{B^2}} = \sqrt{1 + \frac{2E\mu}{L^2} \frac{L^2}{\mu^2 k^2}}$$

$$= \sqrt{1 + \frac{2EL^2}{\mu k^2}}$$

$$\boxed{e=0}$$

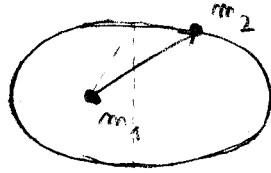
$$1 + \frac{2EL^2}{\mu k^2} = 0$$

$$E = -\frac{1}{2} \frac{\mu k^2}{L^2}$$

$$r = l = \text{cost}$$

\Rightarrow circonferenza di raggio $\frac{l}{\mu k}$

$$\boxed{0 < e < 1}$$



ellisse. H_0

$$r_{\text{max}} = \frac{l}{1-e}$$

$$r_{\text{min}} = \frac{l}{1+e}$$

$$\begin{aligned} \Rightarrow \text{semiasse max} &= \frac{r_{\text{max}} + r_{\text{min}}}{2} = \frac{l(1+e) + l(1-e)}{2(1-e^2)} \\ &\parallel \\ &a \\ &= \frac{l}{1-e^2} \end{aligned}$$

(Relazione tra semiasse max e min dell'ellisse $b = a\sqrt{1-e^2}$)

Altro modo di vederlo:

$$r = \frac{l}{1-e \cos \theta}$$

$$\begin{aligned} x &= r \cos \theta \\ y &= r \sin \theta \end{aligned} \Rightarrow$$

$$\sqrt{x^2 + y^2} - ex = l$$

$$x^2 + y^2 = l^2 + e^2 x^2 + 2lex$$

$$x^2(1-e^2) + 2lex + \frac{l^2 e^2}{(1-e^2)} - \frac{l^2 e^2}{1-e^2} + y^2 = l^2$$

$$\left[x(1-e^2)^{1/2} + \frac{le}{(1-e^2)^{1/2}} \right]^2 + y^2 = l^2 \left(1 + \frac{e^2}{1-e^2} \right)$$

$$(1-e^2) \left[x + \frac{le}{1-e^2} \right]^2 + y^2 = \frac{l^2}{1-e^2}$$

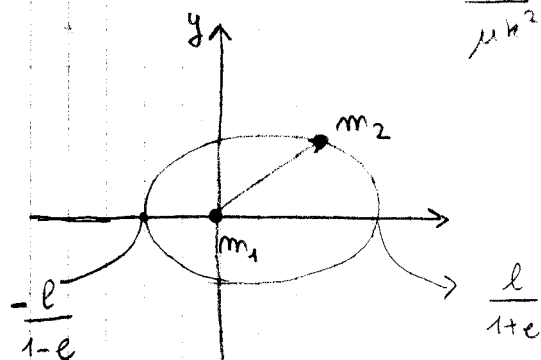
$$X = x + \frac{le}{1-e^2}$$

$$\frac{X^2}{a^2} + \frac{y^2}{b^2} = 1 \quad \text{con}$$

$$\begin{cases} a^2 = \frac{l^2}{(1-e^2)^2} \\ b^2 = \frac{l^2}{1-e^2} \end{cases} \Rightarrow \begin{cases} a = \frac{l}{1-e^2} \\ b = \frac{l}{\sqrt{1-e^2}} \end{cases} \quad b = a \sqrt{1-e^2}$$

$$0 < e < 1 \quad \Leftrightarrow \quad 0 < 1 + \frac{2EL^2}{\mu h^2} < 1$$

$$\Rightarrow \frac{EL^2}{\mu h^2} < 0 \quad E < 0$$



$$\boxed{e > 1} \quad \begin{cases} r \rightarrow \infty \\ \cos \theta = \frac{1}{e} \end{cases} \Rightarrow \text{iperbole}$$

Ma vediamo meglio:

$$\sqrt{x^2 + y^2} - ex = l$$

$$x^2(1-e^2) + 2lex + \frac{l^2 e^2}{(1-e^2)} - \frac{l^2 e^2}{(1-e^2)} + y^2 = l^2$$

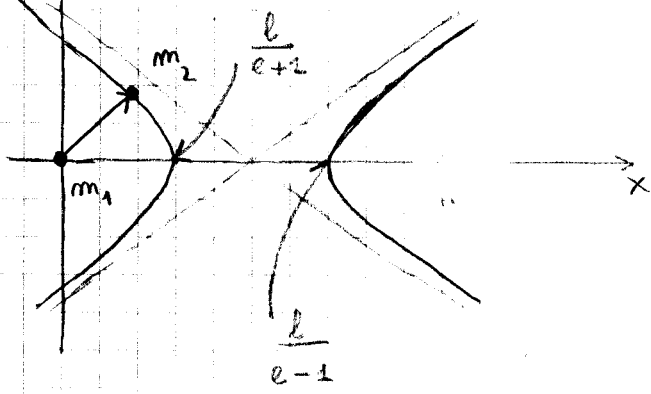
Note che $1-e^2 < 0 \Rightarrow$

$$x^2(e^2-1) - 2lex + \frac{l^2 e^2}{e^2-1} - \frac{l^2 e^2}{e^2-1} - y^2 = -l^2$$

$$(e^2-1) \left[x - \frac{le}{e^2-1} \right]^2 - y^2 = -l^2 \left(1 - \frac{e^2}{e^2-1} \right) = + \frac{l^2}{e^2-1}$$

$$X = x - \frac{le}{e^2-1} \quad \frac{X^2}{a^2} - \frac{y^2}{b^2} = 1 \quad \text{con}$$

$a = \frac{l}{e^2 - 1}$, $b = \frac{l}{\sqrt{e^2 - 1}}$ \rightarrow Iperbole



$y=0 \Rightarrow$

$$x^2 = a^2$$

$$x = \pm a$$

$$x - \frac{le}{e^2 - 1} = \pm \frac{l}{e^2 - 1}$$

$$(e^2 - 1)x = \pm l + le$$

$$x = \begin{cases} \frac{l}{e-1} \\ \frac{l}{e+1} \end{cases}$$

$e > 1 \Rightarrow 1 + \frac{2EL^2}{\mu k^2} > 1 \quad E > 0$

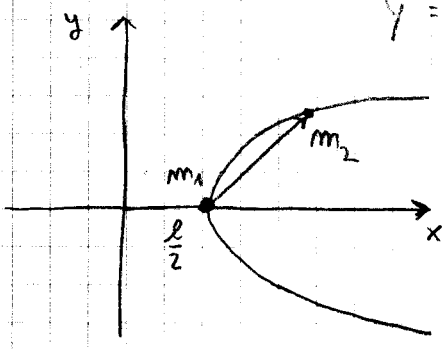
$e = 1 \Rightarrow \tau = \frac{l}{1 - \cos \theta} \Rightarrow \theta = 0 \quad \tau \rightarrow \infty$ parabola

Di nuovo: $\sqrt{x^2 + y^2} - x = l$

$x^2 + y^2 = l^2 + x^2 - 2lx$

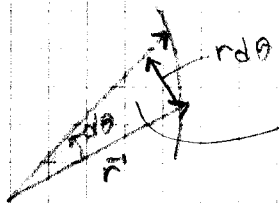
$y^2 = l^2 - 2lx = l \underbrace{(l - 2x)}_x$

$y^2 = lx$



$e = 1 \Rightarrow 1 + \frac{2EL^2}{\mu k^2} = 1 \Rightarrow E = 0$

Definisci cosa da notare: sufficientemente $E < 0$ (\Rightarrow orbite chiuse)



$ds = \frac{1}{2} r^2 d\theta \Rightarrow \dot{s} \equiv$ velocità angolare $= \frac{1}{2} r^2 \dot{\theta}$

$\Rightarrow L = \mu r^2 \dot{\theta} = 2\mu \dot{s} \Rightarrow \dot{s}$ è costante

$\dot{s} = \frac{s}{T} \stackrel{\text{ellisse}}{\downarrow} = \frac{\pi ab}{T} \Rightarrow T = \frac{2\mu \pi ab}{L} = \frac{2\mu \pi a^2 \sqrt{1-e^2}}{\sqrt{\mu k a (1-e^2)}}$

$$T = 2\pi \sqrt{\frac{\mu}{k}} a^{3/2}$$

9

Supponi $m_1 \gg m_2 \Rightarrow \mu = m_2 \leftarrow$ caso delle leggi di Keplero

- 1) Pianeti si muovono su un'orbita ellittica di cui il sole occupa uno dei fuochi [E cost. del moto < 0]
- 2) La velocità angolare è costante [L cost. del moto]
- 3) $T \propto a^{3/2}$ [conseguenza delle precedenti]

Infine

$$a = \frac{l}{1-e^2} = \frac{\cancel{k}^2}{\mu \cancel{k}} \frac{1}{\cancel{k} - \cancel{k} - \frac{2E l^2}{\mu \cancel{k}^2}} = \frac{k}{2|E|}$$

$\Rightarrow a$ dipende solo da E !!